

Bayesian Method for Repeated Threshold Estimation

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Motivation: Perceptual Learning

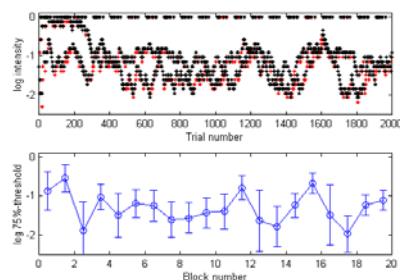
- Non-stationary thresholds
- Dynamics of learning is important
- Must use naïve observers
- Low motivation → high lapsing rates
- Slow learning → many sessions
- Large volume of low-quality binary data

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Objective: Data Reduction



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Isn't This a Solved Problem?

- Up/down (Levitt, 1970)
- PEST (Taylor & Creelman, 1967)
- BEST PEST (Pentland, 1980)
- QUEST (Watson & Pelli, 1979)
- ML-Test (Harvey, 1986)
- Ideal (Pelli, 1987)
- YAAP (Treutwein, 1989)
- and many others...



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We Solve a Different Problem

- Standard methods:
 - Adaptive stimulus placement
 - Stopping criterion
 - Threshold estimation
- Our method:
 - Threshold estimation
 - Integrate information across blocks

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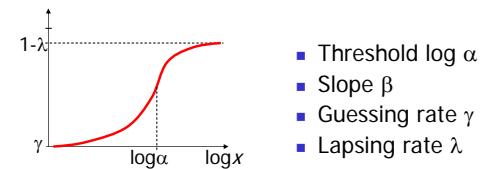
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Weibull Psychometric Function

$$W(x; \alpha, \beta) = 1 - \exp(-\exp((\log x - \log \alpha)\beta))$$

$$P(x; \alpha, \beta, \gamma, \lambda) = \gamma + (1 - \gamma - \lambda)W(x; \alpha, \beta)$$



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Two Kinds of Parameters

- Threshold $\log \alpha$
- Slope β
- Guessing rate γ
- Lapsing rate λ

Parameters of interest θ

Nuisance parameters ϕ

The nuisance parameters are harder to estimate but change more slowly than the threshold parameter.

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Get the Best of Both Worlds



Use long data sequences to constrain the nuisance parameters; use short sequences to estimate the thresholds.

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Joint Posterior of θ_k, ϕ

$$p(\theta_k, \phi | \mathbf{y}_k; \mathbf{y}_1 \dots \mathbf{y}_{k-1}, \mathbf{y}_{k+1} \dots \mathbf{y}_n) = p(\mathbf{y}_k | \theta_k, \phi) p(\theta_k) p(\phi) \prod_{i \neq k} \int p(\theta_i) p(\mathbf{y}_i | \theta_i, \phi) d\theta_i$$

Likelihood of current data Priors Information about ϕ extracted from the other data sets

Modified prior for the current block

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Two-Pass Algorithm

- Pass 1: for each block i , calculate

$$p(\phi | \mathbf{y}_i) = \int p(\theta) p(\mathbf{y}_i | \theta, \phi) d\theta$$
- Pass 2: for each block k , calculate

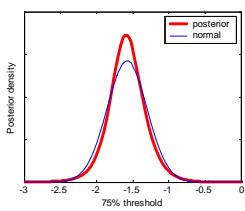
$$p(\theta_k, \phi | \mathbf{y}_k) = p(\mathbf{y}_k | \theta_k, \phi) p(\theta_k) p(\phi) \prod_{i \neq k} \int p(\phi | \mathbf{y}_i)$$

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Posterior Thresholds

$$p(T_k) = \int P^{-1}(.75; \theta_k, \phi) p(\theta_k, \phi | \mathbf{y}_k) d\theta_k d\phi$$


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Some Details

- Vaguely informative priors:
 $p(\log \alpha) \propto N(\mu_\alpha, \sigma_\alpha)$
 $p(\beta) \propto N(\mu_\beta, \sigma_\beta)$
 $p(\lambda) \propto \text{Beta}(a_\lambda, b_\lambda)$
- Implemented on a grid: $\log \alpha \times \beta \times \lambda$
- Assume $\gamma=.5$ for 2AFC data
- MATLAB software available at <http://alexpetrov.com/softw/>

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Simulation 1: Stationary

$\log \alpha = -1.204 = \text{const}$

$\beta = 1.5$

$\lambda = .10$

$T_{75} = -1.217$

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Stimulus Placement

- 2 interleaved staircases
- 100 trials/block
 - 10 catch
 - 40 x 3down/1up
 - 50 x 2down/1up
- 100 runs of 12 blocks each

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Threshold Estimators

Estimator	Mean	Med	Std
ML	-1.24	-1.23	.27
Median	-1.26	-1.23	.28
Mean	-1.30	-1.27	.31
Std. dev.	0.41	0.36	.15

1200 Monte Carlo estimates
True 75% threshold = -1.217

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$\beta \times \lambda$ Distribution from Pass 1

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Catch Trials Are Worthwhile

Estimator	Mean	Med	Std
ML	-1.24	-1.22	.31
Median	-1.29	-1.26	.30
Mean	-1.36	-1.33	.34
Std. dev.	0.58	0.57	.16

1200 Monte Carlo estimates
No catch trials presented
True 75% threshold = -1.217

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Simulation 2: With Learning

$\log \alpha = -0.693 (e^{-t/800} - 2)$

$\beta = 1.5$

$\lambda = .10$

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